

**B.TECH**  
**(SEM IV) THEORY EXAMINATION 2018-19**  
**COMPUTER GRAPHICS**

**Time: 3 Hours****Total Marks: 70****Note: 1.** Attempt all Sections. If require any missing data; then choose suitably.**SECTION A**

- 1. Attempt all questions in brief.** **2 x 7 = 14**
- What are the merits and demerits of LCD?
  - What is the role of pixel and frame buffer in graphic devices?
  - What is the difference between Homogeneous Transformation and Combined Transformation?
  - Why are Homogeneous co-ordinates used for transformation computations in computer Graphics?
  - What is the difference between a window and a view port?
  - What do you understand by shadow mask CRT?
  - What do you mean by composite transformation?

**SECTION B**

- 2. Attempt any three of the following:** **7 x 3 = 21**
- Demonstrate Cohen Sutherland line clipping method with example.
  - What is window to view port coordinate transformation? What are the issues related to multiple windowing.
  - What are the difference between Raster scan and Random scan display?
  - Explain Phong and Warn Illumination model in detail.
  - What are the Geometric primitives in 3-D graphics?

**SECTION C**

- 3. Attempt any one part of the following:** **7 x 1 = 7**
- Draw a simple Illumination model. Include the contribution of Diffuse, Ambient and Specular Reflection.
  - Explain the concept of Transparency and shadows in Hidden line and surfaces.
- 4. Attempt any one part of the following:** **7 x 1 = 7**
- Explain the various 3-D clipping methods with example.
  - Give the brief description of transformation in 3-D graphics.
- 5. Attempt any one part of the following:** **7 x 1 = 7**
- Obtain the mirror reflection of the triangle formed by the vertices A(0,3),B(2,0) and C(3,2) about the line passing through the points (1,3) and (-1, -1).
  - Explain Bresenham's algorithm of line drawing.
- 6. Attempt any one part of the following:** **7 x 1 = 7**
- Obtain a combined transformation matrix if a rotation is perform about an arbitrary point.
  - Prove that 2 successive 2-D rotation are additive ie.,  $R(\theta_1).R(\theta_2) = R(\theta_1 + \theta_2)$
- 7. Attempt any one part of the following:** **7 x 1 = 7**
- List the advantages and disadvantages of back face detection and A-buffer method. Write the algorithm for back face detection.
  - Compare and contrast among spline, B-spline and Bezier algorithms for curve generation and write the algorithm for Bezier curve generation.